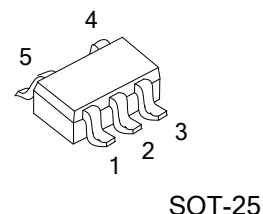




## FAST TURN-OFF INTELLIGENT CONTROLLER

### ■ DESCRIPTION

The **USRC8801** is a Low-Drop Diode Emulator IC that, combined with an external switch replaces Schottky diodes in high-efficiency, Flyback converters. The chip regulates the forward drop of an external switch to about 70mV and switches it off as soon as the voltage becomes negative.



SOT-25

### ■ FEATURES

- \* Works with both Standard and Logic Level FETS
- \* Compatible with Energy Star, 1W Standby Requirements
- \*  $V_{DD}$  Range From 8V to 24V
- \* 70mV VDS Regulation Function
- \* Fast Turn-off Total Delay of 20ns
- \* Max 400kHz Switching Frequency
- \* <3mA Low Quiescent Current
- \* Supports CCM, DCM and Quasi-Resonant Topologies
- \* Supports High-side and Low-side Rectification
- \* Power Savings of Up to 1.5W in a Typical Notebook Adapter

### ■ APPLICATION

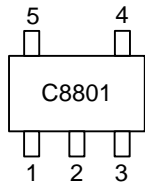
- \* Industrial Power Systems
- \* Distributed Power Systems
- \* Battery Powered Systems
- \* Flyback Converters

### ■ ORDERING INFORMATION

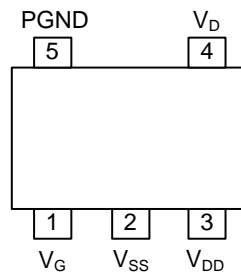
Ordering Number		Package	Packing
Lead Free	Halogen Free		
USRC8801L-AF5-R	USRC8801G-AF5-R	SOT-25	Tape Reel

USRC8801G-AF5-R		(1) Packing Type	(1) R: Tape Reel
		(2) Package Type	(2) AF5: SOT-25
		(3) Green Package	(3) G: Halogen Free and Lead Free, L: Lead Free

## ■ MARKING



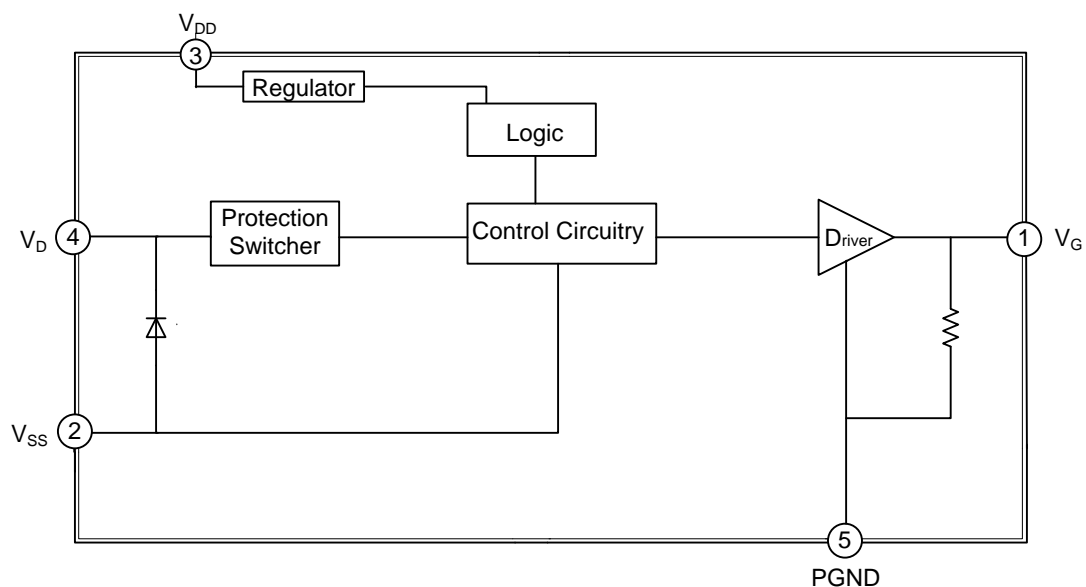
## ■ PIN CONFIGURATION



## ■ PIN DESCRIPTION

PIN NO.	PIN NAME	TYPE	DESCRIPTION
1	$V_G$		Gate drive output
2	$V_{SS}$	I	Ground, also used as reference for VD
3	$V_{DD}$	I	Supply Voltage
4	$V_D$	I/O	FET drain voltage sense
5	$PGND$	I/O	Power Ground, return for driver switch

## ■ BLOCK DIAGRAM



### ■ ABSOLUTE MAXIMUM RATINGS ( $T_A=25^{\circ}\text{C}$ , unless otherwise specified)

PARAMETER	SYMBOL	RATINGS	UNIT
$V_{DD}$ to $V_{SS}$	$V_{DD}-V_{SS}$	-0.3 ~ +27	V
PGND to $V_{SS}$	$V_{PGND}-V_{SS}$	-0.3 ~ +0.3	V
$V_G$ to $V_{SS}$	$V_G-V_{SS}$	-0.3 ~ $V_{CC}$	V
$V_D$ to $V_{SS}$	$V_D-V_{SS}$	-0.7 ~ +180	V
EN to $V_{SS}$	$V_{EN}-V_{SS}$	-0.3 ~ +6.5	V
Maximum Operating Frequency	$f_{MAX}$	400	kHz
Power Dissipation	$P_D$	0.57	W
Operating Junction Temperature	$T_J$	+150	$^{\circ}\text{C}$
Storage Temperature	$T_{STG}$	-55 ~ +125	$^{\circ}\text{C}$

Note: Absolute maximum ratings are those values beyond which the device could be permanently damaged.  
Absolute maximum ratings are stress ratings only and functional device operation is not implied.

### ■ RECOMMENDED OPERATING RATINGS

PARAMETER	SYMBOL	RATINGS	UNIT
$V_{DD}$ to $V_{SS}$	$V_{IN}$	8 ~ 24	V
Operating Junction Temperature	$T_J$	-40 ~ +125	$^{\circ}\text{C}$

### ■ THERMAL DATA

PARAMETER	SYMBOL	RATINGS	UNIT
Junction to Ambient	$\theta_{JA}$	220	$^{\circ}\text{C/W}$
Junction to Case	$\theta_{JC}$	110	$^{\circ}\text{C/W}$

### ■ ELECTRICAL CHARACTERISTICS ( $V_{DD}=12\text{V}$ , $T_A=25^{\circ}\text{C}$ , unless otherwise specified)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{DD}$ Voltage Range	$V_{DD}$		8		24	V
$V_{DD}$ UVLO Rising	$V_{UVLO}$		5.0	6.0	7.0	V
$V_{DD}$ UVLO Hysteresis	$V_{UVLO\_HS}$			1.2		V
Operating Current	$I_{CC}$	$C_{LOAD}=5\text{nF}$ , $F_{SW}=100\text{kHz}$		8	12	mA
Quiescent Current	$I_{NS}$	No Switching		2	3	mA
Shutdown Current	$I_{SD}$	$V_{DD}=4\text{V}$		100	150	$\mu\text{A}$
$V_{DD}=20\text{V}$	$I_{EN}$	EN=0V (50 k $\Omega$ )			250	$\mu\text{A}$
Thermal Shutdown	$T_{SD}$			170		$^{\circ}\text{C}$
Thermal Shutdown hysteresis	$T_{HS}$			50		$^{\circ}\text{C}$

#### CONTROL CIRCUITRY SECTION

$V_{SS}-V_D$ Forward Voltage, $V_{fwd}$	$V_{FWD}$		55	70	85	mV
Turn-on Delay	$T_D$	$C_{LOAD}=5\text{nF}$		150		ns
		$C_{LOAD}=10\text{nF}$		200		ns
Pull-down Resistance of $V_G$ Pin	$R_{PD}$			10	20	k $\Omega$
Input Bias Current On $V_D$ Pin	$I_{IN}$	$-0.3\text{V} > V_D > 180\text{V}$			10	$\mu\text{A}$
Minimum On-time	$T_{ON}$	$C_{LOAD}=5\text{nF}$		1.6		$\mu\text{s}$

#### GATE DRIVER SECTION

$V_G$ (Low)	$V_{GL}$	$I_{LOAD}=1\text{mA}$		0.05	0.5	V
$V_G$ (High)	$V_{GH}$	$V_{DD}>17\text{V}$	12	13.5	15	V
		$V_{DD}<17\text{V}$	$V_{DD}-2.2$			V
Turn-off Threshold ( $V_{SS}-V_D$ )	$V_{SS}-V_D$		20	30	40	mV
Turn-off Propagation delay	$T_{GP}$	$V_D=V_{SS}$ , $R_{GATE}=0\Omega$		15		ns
Turn-off Total Delay	$T_{GD}$	$V_D=V_{SS}$ , $C_{LOAD}=5\text{nF}$ , $R_{GATE}=0\Omega$		20	35	ns
		$V_D=V_{SS}$ , $C_{LOAD}=10\text{nF}$ , $R_{GATE}=0\Omega$		30	45	ns
Pull Down Impedance	$R_{PDI}$			1	2	$\Omega$
Pull Down Current	$I_{PD}$	$3\text{V} < V_G < 10\text{V}$		2		A

## ■ APPLICATION INFORMATION

The **USRC8801** supports operation in CCM, DCM and Quasi-Resonant topologies. Operating in either a DCM or Quasi-Resonant topology, the control circuitry controls the gate in forward mode and will turn the gate off when the MOSFET current is fairly low. In CCM operation, the control circuitry turns off the gate when very fast transients occur.

### Blanking

The control circuitry contains a blanking function. When it pulls the MOSFET on/off, it makes sure that the on/off state at least lasts for some time. The turn on blanking time is  $\sim 1.6\mu\text{s}$ , which determines the minimum on-time. During the turn on blanking period, the turn off threshold is not totally blanked, but changes the threshold voltage to  $\sim +50\text{mV}$  (instead of  $-30\text{mV}$ ). This assures that the part can always be turned off even during the turn on blanking period. (Albeit slower, so it is not recommended to set the synchronous period less than  $1.6\mu\text{s}$  at CCM condition in flyback converter, otherwise shoot through may occur)

### $V_D$ CLAMP

Because  $V_D$  can go as high as  $180\text{V}$ , a High-Voltage JFET is used at the input. To avoid excessive currents when  $V_g$  goes below  $-0.7\text{V}$ , a small resistor is recommended between  $V_D$  and the drain of the external MOSFET.

Under-Voltage Lockout (UVLO)

When the  $V_{DD}$  is below UVLO threshold, the part is in sleep mode and the  $V_g$  pin is pulled low by a  $10\text{k}\Omega$  resistor.

Thermal shutdown

If the junction temperature of the chip exceeds  $170^\circ\text{C}$ , the  $V_g$  will be pulled low and the part stops switching. The part will return to normal function after the junction temperature has dropped to  $120^\circ\text{C}$ .

### Turn-on Phase

When the synchronous MOSFET is conducting, current will flow through its body diode which generates a negative  $V_{DS}$  across it. Because this body diode voltage drop ( $< -500\text{mV}$ ) is much smaller than the turn on threshold of the control circuitry ( $-70\text{mV}$ ), which will then pull the gate driver voltage high to turn on the synchronous MOSFET after about  $150\text{ns}$  turn on delay.

As soon as the turn on threshold ( $-70\text{mV}$ ) is triggered, a blanking time (Minimum on-time:  $\sim 1.6\mu\text{s}$ ) will be added during which the turn off threshold will be changed from  $-30\text{mV}$  to  $+50\text{mV}$ . This blanking time can help to avoid error trigger on turn off threshold caused by the turn on ringing of the synchronous MOSFET.

### Conducting Phase

When the synchronous MOSFET is turned on,  $V_{DS}$  becomes to rise according to its on resistance, as soon as  $V_{DS}$  rises above the turn on threshold ( $-70\text{mV}$ ), the control circuitry stops pulling up the gate driver which leads the gate voltage is pulled down by the internal pull-down resistance ( $10\text{k}\Omega$ ) to larger the on resistance of synchronous MOSFET to ease the rise of  $V_{DS}$ .

By doing that,  $V_{DS}$  is adjusted to be around  $-70\text{mV}$  even when the current through the MOS is fairly small, this function can make the driver voltage fairly low when the synchronous MOSFET is turned off to fast the turn off speed (this function is still active during turn on blanking time which means the gate driver could still be turned off even with very small duty of the synchronous MOSFET).

### Turn-off Phase

When  $V_{DS}$  rises to trigger the turn off threshold ( $-30\text{mV}$ ), the gate voltage is pulled to low after about  $20\text{ns}$  turn off delay by the control circuitry. Similar with turn-on phase, a  $200\text{ns}$  blanking time is added after the synchronous MOSFET is turned off to avoid error trigger.

Due to the high current, the gate driver will be saturated at first. After  $V_{DS}$  goes to above  $-70\text{mV}$ , gate driver voltage decreases to adjust the  $V_{DS}$  to typical  $-70\text{mV}$ .

Due to the low current, the gate driver voltage never saturates but begins to decrease as soon as the synchronous MOSFET is turned on and adjust the  $V_{DS}$ .

**■ APPLICATION INFORMATION (Cont.)****SR MOSFET Selection and Driver ability**

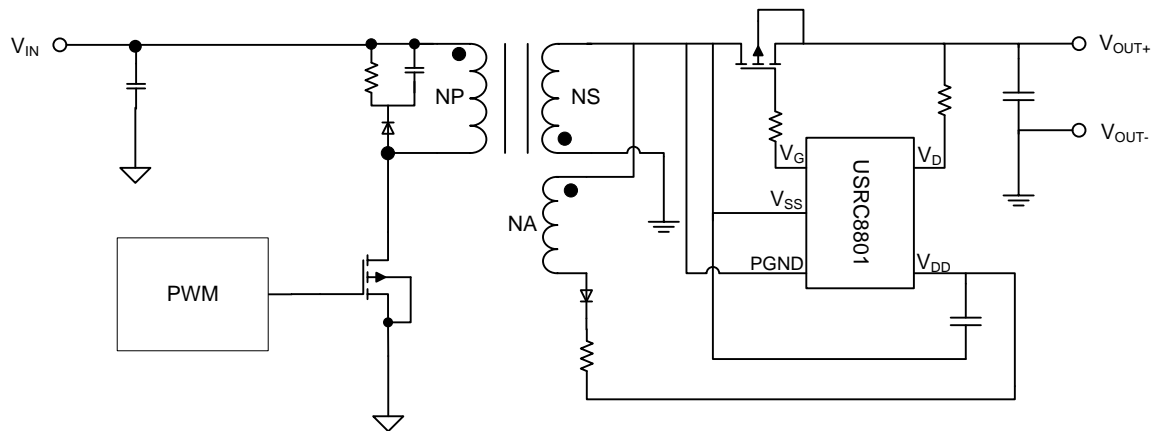
The Power MOSFET selection proved to be a trade off between  $R_{on}$  and  $Q_g$ . In order to achieve high efficiency, the MOSFET with smaller  $R_{on}$  is always preferred, while the  $Q_g$  is usually larger with smaller  $R_{on}$ , which makes the turn-on/off speed lower and lead to larger power loss. For **USRC8801**, because  $V_{DS}$  is regulated at  $\sim -70mV$  during the driving period, the MOSFET with too small  $R_{on}$  is not recommend, because the gate driver may be pulled down to a fairly low level with too small  $R_{on}$  when the MOSFET current is still fairly high, which make the advantage of the low  $R_{on}$  inconspicuous.

Assume 50% duty cycle and the output current is  $I_{OUT}$ .

To achieve fairly high usage of the MOSFET'S  $R_{on}$ , it is expected that the MOSFET be fully turned on at least 50% of the SR conduction period:

$$V_{DS} = -I_C \times R_{on} = -2 \cdot I_{OUT} \times R_{on} \leq -V_{fwd}$$

## ■ TYPICAL APPLICATION CIRCUIT



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